

Scotland's Rural College

Precision Agriculture Technologies positively contributing to GHG emissions mitigation, farm productivity and economics

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Published in:
Sustainability

DOI:
[10.3390/su9081339](https://doi.org/10.3390/su9081339)

First published: 31/07/2017

Document Version
Publisher's PDF, also known as Version of record

[Link to publication](#)

Citation for published version (APA):

Balafoutis, A., Beck, B., Fountas, S., Vangeyte, J., van der Wal, T., Soto-Embodas, I., Gomez-Barbero, M., Barnes, AP., & Eory, V. (2017). Precision Agriculture Technologies positively contributing to GHG emissions mitigation, farm productivity and economics. *Sustainability*, 9(8), 1 - 7. Advance online publication. <https://doi.org/10.3390/su9081339>

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1 *Review*

2 **Precision Agriculture Technologies positively** 3 **contributing to GHG emissions mitigation, farm** 4 **productivity and economics**

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19 Academic Editor: Konstantinos G. Arvanitis, Spyros Fountas

20 Received: date; Accepted: date; Published: date

21 **Abstract:** Agriculture is one of the economic sectors that affects climate change contributing to
22 greenhouse gas emissions directly and indirectly. There is a trend of agricultural greenhouse gas
23 emissions reduction, but any practice in this direction should not affect negatively farm
24 productivity and economics because this would limit its implementation, due to the high global
25 food and feed demand and the competitive environment in this sector. Precision agriculture
26 practices using high-tech equipment has the ability to reduce agricultural inputs by site-specific
27 applications, as it better target inputs to spatial and temporal needs of the fields, which can result in
28 lower greenhouse gas emissions. Precision agriculture can also have a positive impact on farm
29 productivity and economics as it provides higher or equal yields with lower production cost than
30 conventional practices. In this work, the precision agriculture technologies that have the potential
31 to mitigate greenhouse gas emissions are presented providing a short description of the technology
32 and the impacts that have been reported in literature on greenhouse gases reduction and the
33 associated impacts on farm productivity and economics. The technologies presented span between
34 all agricultural practices, including variable rate sowing/planting, fertilizing, spraying, weeding
35 and irrigation.

36 **Keywords:** Precision Agriculture Technologies, Greenhouse Gas Emissions, Farm Productivity,
37 Variable Rate Nutrient Application, Variable Rate Irrigation, Variable rate pesticide application,
38 Variable rate planting/seeding, Precision Physical Weeding

40 1. Introduction

41 Climate change affects all processes on the Earth, including agriculture that will have to adapt
42 to new climatic conditions over the coming years. Agriculture is liable for climate change as its
43 activities accounts for nearly 13.5% of the total global anthropogenic Greenhouse Gas (GHG)
44 emissions [1]. During the last decade, there is a trend of GHG emissions reduction in the agricultural

45 sector, but more effort on this direction should be put in order to fulfil global climate commitments.
46 The main distribution of agricultural GHG emissions is related to cropland soil, enteric fermentation
47 and manure management [2].

48 The application of precision agriculture (PA) practices, using the large reservoir of Precision
49 Agriculture Technologies (PATs) in agricultural field operations could positively contribute to GHG
50 emission reduction due to the ability of soils to operate as carbon stock reserve [2], the reduction of
51 fuel consumption (direct GHG decrease) and the reduction of inputs (indirect GHG decrease) for the
52 agricultural field operations [3]. On the other hand, these practices affect farm productivity by
53 optimizing agricultural inputs that is reflected in higher or equal yields with lower cost than
54 conventional practices. There is a series of GHG mitigation measures that refer to new technologies
55 and techniques on all agricultural practices (precision/variable rate sowing/planting, fertilizing,
56 spraying and irrigation). These innovations can reduce significantly the amount of inputs that are
57 responsible for GHG contribution and could help on the goal of minimum climate change impact of
58 agriculture, always taking into account that crop production should be maintained or even increased
59 in the challenge of ensuring food security and safety for human alimentation.

60 The existing situation of PA practices in the world and EU basis is in general unclear. There was
61 a strong uptake of PATs during the 1990s mainly in North America, because at that time information
62 technology globally had reached high readiness level to invade new economic sectors (except office
63 and industry sectors) and US and Canadian agriculture had the characteristics to promote new
64 technologies promising better economic results. The main characteristics were the large farm sizes,
65 the organised extension system mainly by the government and the Universities, the
66 farmers/entrepreneurs willingness for progress and technology adoption, the high income, the
67 possibility of financing investment and the limited or absent subsidies in agricultural products [4].
68 PA growth rate flattened during the first years of 2000s, because the results (productivity increase,
69 inputs reduction, fuel use decrease, ease of use of PATs, low maintenance, compatibility between
70 brands) were not as positive as expected by the agricultural community. However, PATs are
71 currently taking up again, because technology problems have been gradually resolved both in terms
72 of software and hardware with less compatibility issues, while more tangible economic results at
73 farm level have been shown to practitioners that have positive impact in yield, input and profit. This
74 uptake can be seen by the fact that PA is an important sector in growth with researchers estimating
75 the PA market already amounted to €2.3 billion in 2014 on a global level, with expected growth at an
76 annual growth rate of 12% through 2020 with the mature US and European markets considered as
77 the most promising [5,6].

78 However, most practitioners do not have a clear perspective of the benefits of PATs in
79 agricultural production and do not consider the environmental reimbursements that their use could
80 provide [7-9] developing the need to produce evidence of the actual impact of these technologies on
81 GHG emissions, farm productivity and economics. Therefore, the objective of this paper was to
82 identify and describe the PATs that possess the capacity to have positive impact on GHG emissions
83 produced from the agricultural sector in combination with farm productivity and income sustenance
84 or improvement.

85 In the first section, the main sources of GHG emissions in the agricultural sector are described,
86 while the second section analyses the GHG mitigation practices. Subsequently, the typology PATs is
87 presented in order to sort the PATs that have a potential direct positive impact on GHG emission
88 mitigation combined with improved or at least stable farm productivity and economics. Then, a list
89 of the most influencing PATs is presented with a short description of the technical characteristics of
90 each PAT and subsequently its environmental impacts (focusing on GHG emissions). It should be
91 noted that literature on PATs impact on GHG emissions is highly limited and therefore the
92 discussion on the mitigation capacity of the different PATs is mainly based on the reduction of
93 agricultural inputs (fertilisers, pesticides, fuel, water, etc.) that can be achieved using PATs.
94 Subsequently, the farm productivity and economic impacts of acquiring and using PATs are
95 analyzed and discussed. Finally, a discussion is underlined of the importance of PATs on both
96 reducing GHG emissions and maintaining or increasing farm productivity and income.

97 2. Main Sources of Agricultural GHG emissions

98 The major GHGs produced in the agricultural sector are methane (CH₄), nitrous oxide (N₂O)
99 and carbon dioxide (CO₂). CH₄ is mainly produced from the anaerobic decomposition of organic
100 matter during enteric fermentation and manure management, but also from paddy rice cultivation;
101 N₂O arise from the microbial transformation of N in soils and manures (during the application of
102 manure and synthetic fertiliser to land) and via urine and dung deposited by grazing animals; and
103 CO₂ arising from (a) energy use pre-farm, on-farm and post-farm and (b) from changes in above and
104 below ground carbon stocks induced by land use and land use change [10].

105 The agricultural sector contributes to the production of 25% of CO₂, 50% of CH₄, and 70% of
106 N₂O emissions in a global basis summing up to nearly 13.5% of the total global anthropogenic GHG
107 emissions [1]. However, in OECD member countries agriculture produces 8% of the total GHG
108 emissions with a decline between 2000 and 2010 by an average of 0.4% per annum with
109 simultaneous agricultural production increase of 1.6% per annum, which is interpreted into 1.97% of
110 GHG emission intensity reduction. Therefore, the developed country members of OECD are trying
111 to achieve synchronized GHG mitigation and productivity increase, which is the ideal situation and
112 is defined as the “absolute decoupling” [11].

113 The larger agricultural economies generally produce higher levels of GHG emissions, but they
114 do not follow the same pattern. An explanation of this statement is that France and Germany
115 together accounted for around one third of the EU-28 agricultural GHG emissions, while the
116 combination of the UK, Spain, Poland and Italy covered an additional third of the total. The EU
117 Roadmap for moving to a low carbon economy recommends a reduction target of agricultural GHG
118 emissions by 36-37 % until 2030, and a more ambitious one (42-49 %) for 2050 in comparison to 1990
119 levels (EU Roadmap for 2050).

120 N₂O is the main GHG related to agricultural soil emissions, essentially due to microbial
121 transformation of nitrogen in the soil (the process of nitrification and denitrification to be analysed
122 later in this paper). This concerns nitrogen mineral fertilisers, manure spreading and nitrogen from
123 crop residues incorporated into the soil or lixiviation of surplus nitrogen. N₂O has high Global
124 Warming Potential (298 times higher than CO₂) and it should be minimized to reduce agricultural
125 GHG emissions in total. An example of favourable N₂O increase conditions is when soil temperature
126 is increased and high moisture conditions exist during cooler months. Another example would be
127 the increase of N₂O from upland agricultural soils due to CO₂ concentration [12]. In addition,
128 application of mineral nitrogen in the form of chemical fertilisers increases the N₂O emissions.

129 Enteric fermentation, which is a natural part of the digestive process for ruminants, is the most
130 important CH₄ producer. CH₄ is also produced during manure storage (decomposition). There are
131 several studies targeting on CH₄ measurements [13] and its mitigation from rice fields, mainly
132 through water [14], fertiliser, and manure managements [15]. CH₄ emissions increase when
133 mulching and organic manure are applied in soils [16]. On the other hand, midseason drainage can
134 cut CH₄ emissions significantly [17]. Aerobic soils may act as CH₄ sinks [13,18] or sources [19].

135 As for CO₂, direct combustion of hydrocarbons is the main source together with soil respiration
136 and residual biomass decomposition. However, the majority of the farm operations and inputs (e.g.
137 fertilisers, pesticides, energy, etc.) also have embodied CO₂ content. Direct CO₂ consumed by
138 agriculture as well as indirect CO₂ emissions from processing of inputs at farm level showed that
139 this gas can represent between 10 and 20% of the total GHG emissions in agriculture [2].

140 3. Greenhouse Gases mitigation practices

141 Climate change can be mitigated through the reduction of GHG emissions, the enhancement of
142 GHG removals and the avoidance or displacement of emissions [18]. Mismanagement of carbon (C)
143 and nitrogen (N) flows in the agricultural system is the reason for GHG overproduction. There are
144 methods and technologies that reduce GHG emissions, such as the timely and accurate application
145 of nitrogen fertilization that reduces N₂O [20,21]. Regarding enhancing GHG removals, any
146 agricultural practice that increases photosynthetic processes or slows the return of stored C in
147 organic biomass can be considered as C sequestration method [22]. GHG emissions can be avoided

148 or displaced by the conversion of residual agricultural biomass into biofuel of any type [23,24] where
149 in reality this energy source replace fossil fuels of the same energy content.

150 However, the mechanisms that reduce one GHG can sometimes affect another GHG in a
151 negative way through different mechanisms resulting in combined effects that are unknown [25,26].
152 For instance, no-tillage practices, which can potentially reduce GHG emissions by 20.6-23.7%
153 compared to conventional tillage [27] may have unanticipated and unwanted effects on other
154 sources or sinks of GHG. If, for example, soil water conservation associated with no-till were to
155 provide more moisture for nitrifying and denitrifying bacteria as well as plants, then production of
156 N₂O might increase, offsetting some or all of the mitigation potential of carbon storage [28].

157 Smith et al. (2008) [18] listed the GHG emissions mitigation measures in seven categories that
158 include different practices. More particularly, cropland management (nutrient management,
159 tillage/residue management, water management, rise management, agroforestry, set-aside, land-use
160 change), grazing land management/pasture improvement (grazing intensity, increased productivity
161 through fertilisation, nutrient management, fire management, species introduction including
162 legumes), management of organic soils (avoid drainage of wetlands), restoration of degraded lands
163 (erosion control, organic amendments, nutrient amendments), livestock management (improved
164 feeding practices, specific agents and dietary additives, longer term structural and management
165 changes and animal breeding), manure/biosolid management (improved storage and handling,
166 anaerobic digestion, more efficient use as nutrient source) and bioenergy (energy crops, solid, liquid,
167 biogas, residues).

168 PA for crop farming is included in the first category with a special interest on nutrient
169 management and water management. Agricultural GHG emission mitigation focus should be on
170 increasing the efficiency of agriculture in order to reduce future land conversion, and also on
171 reducing N₂O emissions from soil N management [29]. They considered four (4) mitigation
172 measures connected with PA (improved timing of mineral N application, improved timing of
173 organic N application, full allowance of manure N supply and avoiding N excess). All of them
174 showed considerable abatement rates with “Improved timing of mineral N application” reaching 0.3
175 tCO₂-eq/ha.

176 Another report [30] indicated some mitigation methods in order to reduce agricultural
177 production emissions in the UK by 3 MtCO₂-eq until 2020 compared to 2007 and showed that the
178 most promising for GHG reduction (it can reach 1.4 MtCO₂-eq) in high extend is nutrient
179 management, followed by the use of plants with improved nitrogen use efficiency (potential of 0.8
180 MtCO₂-eq) and improved land and soil management (up to 0.45 MtCO₂-eq). This work shows the
181 potential of PA practices that are directly connected with nutrient, land and soil management.

182 The European Commission Climate Action also proposes GHG mitigation measures related to
183 farming practices, like seeding/planting, harvesting, irrigation and fertilisation of existing crops, use
184 of different varieties, diversify crops, implement management practices. EU seeks for sustainable
185 agricultural schemes through the new Common Agricultural Policy (CAP). Natural resources are
186 depleting and agriculture has to improve its environmental performance. Sustainable management
187 of natural resources and climate action represent one of the three main objectives of the CAP.
188 Improved sustainability will be achieved firstly by covering certain environmental requirements and
189 obligations in order to receive full CAP funding. Secondly, from 2015 onwards, the CAP introduced
190 a new policy instrument, the Green Direct Payment, that is granted only when there is simultaneous
191 crop diversification, ecological focus areas and permanent grassland, with environmental benefits
192 on biodiversity, water and soil quality, carbon sequestration and landscapes. It represents 30% of the
193 direct payment budget and it is compulsory. Finally, rural development is vital for achieving the
194 environmental objectives of the CAP and combating climate change as at least 30% of the budget of
195 each rural development programme must be reserved for targeted measures on this direction. All
196 these policy instruments are accompanied by related training measures and other
197 support from the Farm Advisory System, insights gained from the Innovation
198 Partnership and applied research, which would help farmers to implement appropriate
199 solutions for their specific situations. Proposed solutions on the farm level are the adjustment of

200 farm operations timing; the improvement of the effectiveness of pest and disease control through
201 better monitoring, diversified crop rotations, or integrated pest management methods; the use of
202 water more efficiently by reducing water losses, improving irrigation practices, and recycling or
203 storing water; and the improvement of soil management by increasing water retention to conserve
204 soil moisture.

205 PATs could participate in the achievement of agricultural sustainability as they interfere in
206 most agricultural practices by reducing or redistributing inputs to address the real requirements of
207 the crop. It is anticipated that the new CAP will promote further PATs as one of the methods to
208 increase or maintain productivity with simultaneous reduction of environmental impacts, and in
209 specific GHG emissions.

210 4. Typology of Precision Agriculture Technologies

211 In the literature there are only three attempts to provide a typology of PATs. One of the most
212 prominent studies on PA [7] classifies PATs in three main categories: *Hardware and sensors* (i.e.
213 positioning and guidance, crop sensing for water stress, nutrients and yield sensing, environmental
214 sensing, seed bed preparation, fertiliser placement in the soil profile); *Data Analysis and Decision*
215 *Support Systems* (i.e. protocols and standards for field data layers production, methods for data
216 analysis for delineation of management zones, easy-to-use software); *Commodity and whole-farm focus*
217 (i.e. development of DSS to apply commercially in farms including environmental impact
218 assessment, apply PA at farm level and not at field level).

219 Zarco-Tejada et al. (2014) [9] categorised PATs for crop and livestock farming in a linear manner
220 following the timeline of use of the technologies ending up in three categories, namely *Remote*
221 *sensing*; *Guidance systems*; *Variable rate applications*. Finally, Schwarz et al. (2011) [31] have provided
222 the most comprehensive typology of PATs (selected to be used in this work), divided into three main
223 categories: *Guidance systems* (i.e. hard- and software that guide tractors and implements over a field),
224 which include all forms of automatic steering/guidance for tractors and self-propelled agricultural
225 machinery, such as driver assistance, machine guidance, controlled traffic farming; *Recording*
226 *technologies* (i.e. sensors mounted on ground-based stations, rolling, airborne or satellite platforms,
227 gathering spatial information), which include soil mapping, soil moisture mapping, canopy
228 mapping, yield mapping, etc.; *Reacting technologies* (i.e. implements, hard- and software that together
229 can vary the placement of agricultural inputs in the field), which include technologies like variable
230 rate irrigation and weeding and variable rate application of seeds, fertiliser and pesticides.

231 Recording technologies are required in order to receive information from the field (before,
232 during and after the crop period) and after processing, extract the data useful for any kind of PA
233 application. On the other hand, guidance technologies can be used for any agricultural practice
234 application (including traditional practices) focusing on precise machinery movement within and
235 between fields with tangible results in reduced overlapping causing lower input use (seeds,
236 fertilisers, pesticides) in parallel with decreased self-propelled machinery fuel consumption. Finally,
237 the reacting technologies are supposed to use the data produced by the recording systems and
238 minimize all inputs (seeds, fertilisers, pesticides, water) in the optimum quantity required by the
239 crop to grow. The right combination of these three categories is expected to increase or at least
240 maintain yield with the advantage of higher quality.

241 All the PATs that are included in the typology of Schwarz et al. (2011) [31] together with their
242 interconnection are summarized in Figure 1. All three categories of PATs require the use of Global
243 Navigation Satellite Systems (GNSSs), as shown in the figure.

244

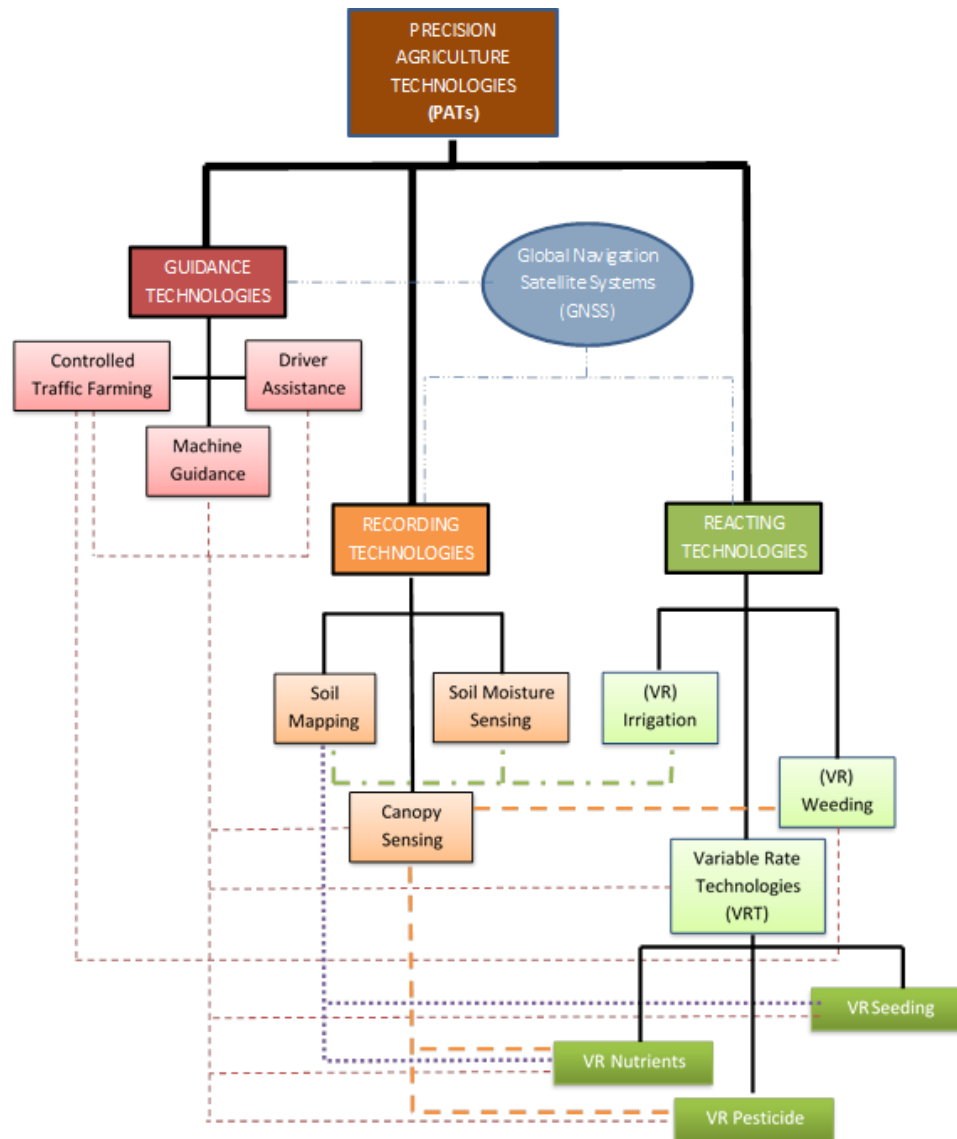


Figure 1. Precision agriculture technologies overview

All PATs contribute in the final quantity and quality of yield due to their interconnections and it is difficult to separate them according to importance. Therefore, the main criterion to select the PATs that have the potential to reduce GHG emissions increasing or maintaining farm productivity was the direct impact on aforementioned both parameters.

As recording technologies remain supportive in the PA process, it was decided not to be analysed in the next section of this paper. For the same reasons GNSSs were also excluded from further analysis. Hence, reacting technologies and guidance systems were selected to be analysed and their potential to reduce GHG emissions and improve farm productivity and income was assessed.

5. Impacts of the selected precision agriculture technologies

In this section we present the PATs that could increase/maintain farm productivity and simultaneously reduce GHG emissions. At first, a short technical description of each technology is given. Then, further analysis of the literature on impacts of PATs (where applicable) that can mitigate GHGs together with discussion on behalf of the authors is given. Prices of the selected PATs, together with the source, are provided in the Annex.

264 5.1. Variable rate nutrient application (VRNA)

265 5.1.1. Description of VRNA technologies

266 Variable rate nutrient application (VRNA) can provide to the field inorganic fertilisers (N, P, K),
267 manure and lime by adjusting the mass flow rate and subsequently the application rate of nutrients
268 according to the specific needs of the crop locally within the field. Inorganic fertiliser is either spread
269 as liquid or solid granules, while manure is spread as slurry or solid manure. VR liquid inorganic
270 fertiliser is spread using VR pesticide sprayer technology (mentioned later).

271 VRNA is executed by either applying a prescription map that was designed after receiving data
272 from the field using mainly canopy sensors that identify the status of the crop and correlate it with
273 nutrient needs or by combining the recording and reacting procedure on-the-go, meaning
274 simultaneously.

275 Inorganic fertilizers and lime are distributed in the field using two main technologies; the
276 *spinner or centrifugal spreaders* that are based on a conveyer belt or chain that transfers the material
277 (granules) from the hopper until it falls on one or more spinning disks throwing the particles into the
278 field and the *pneumatic spreaders* that use airflow which divides the granules over a piped spreading
279 boom for uniform distribution [32,33]. VRNA in spinner spreaders the application rate is controlled
280 by adjusting the gate opening and/or changing the speed of the conveyor (and thus the input rate of
281 material). In pneumatic applicators VRNA is executed by spreading the material using an adjustable
282 controlled air stream through a piped boom [34].

283 As for slurry distribution in the field, the applicators work by either pressuring the slurry tank
284 (by changing the size of the gate that brings slurry to the delivery system) or by pumping the slurry
285 from the tank (by changing pump or valve settings). Solid manure spreaders work with an apron
286 that pushes the manure towards a dispensing system [35-36]. VRNA is based on changing the
287 required slurry flowrate based on an application map or real-time soil sensors, combined with
288 simultaneous measurements of the nitrogen content of the slurry, the ground speed and working
289 width of the vehicle [35-36].

290 5.1.2. GHG emissions reduction potential through VRNA

291 Nitrogen fertilisation is the most significant parameter producing GHG emissions in the
292 agricultural sector, as nitrogen inorganic fertilisers are the cause of CO₂ and N₂O emissions during
293 their production and N₂O emissions after their application in the soil [10,29,37].

294 295 *GHG emissions from nitrogen fertiliser production*

296 In order to produce N fertilisers, it is required to synthesize ammonia, where CO₂ is produced
297 from the use of fossil energy sources (mainly natural gas) as feedstock and fuel. Methane provides
298 60% of the required H₂ (together with 40% from water steam) to react with atmospheric N₂ and
299 produce ammonia. A portion of CH₄ is used to heat the process. On the other hand, nitric acid
300 production process is the source of N₂O emissions [37]. Ammonium nitrate (AN-N), which is the
301 base of nitrogen fertilisers, can be produced at different levels of technology and the emitted GHGs
302 are different in each case.

303 Technology advancement has decreased total GHG emissions from 7.9 t CO₂-eq/t AN-N to a
304 level below 3 t CO₂-eq/t AN-N, which can be achieved by adopting de-N₂O catalyst systems that
305 reduce N₂O emissions from nitric acid production using catalytic systems that break down N₂O
306 under high temperature into harmless nitrogen (N₂) and oxygen (O₂). These systems are being fitted
307 to many nitric acid plants and virtually all operating plants in Europe had abatement systems since
308 the mid-2010s. The respective GHG emissions from wheat production at the economic optimum N
309 fertilizer application rate when de-N₂O technology is applied are significantly reduced by about
310 40%, from 2.55 t CO₂-eq/ha it was reduced to 1.6 t CO₂-eq/ha [37].

311 Therefore, if variable rate nitrogen fertilization is applied in combination with the fitting of
312 de-N₂O catalytic systems in the production line of N fertilizers, the result in the total GHG emissions
313 derived by N application is expected to be even more positive.

314

315 *GHG emissions from nitrogen fertiliser application*

316 Inorganic or organic N within soil is subject to various natural microbial conversion processes,
317 some of which may produce N₂O. The main inorganic forms of N in the soil are ammonium (NH₄⁺)
318 and nitrate (NO₃⁻). Ammonium originates either directly from mineral fertilisers, from the
319 conversion of manure or crop residues or from urea fertilisers. Nitrate is either directly applied as
320 nitrate mineral fertiliser or results from the microbial oxidation of ammonium. Nitrate is dissolved
321 in the water in the soil and cannot be stored in the soil over the long term. During the period of crop
322 growth, nitrate is taken up at high rates. However, at times of low or zero crop demand, and under
323 certain environmental conditions, nitrate can be lost either to the air via denitrification or to water by
324 leaching. Ammonium is not mobile and most of it has to be converted into nitrate before crops can
325 take it up. Losses of ammonium from the soil occur via volatilisation of ammonia (NH₃).

326 Nitrification is the oxidation of ammonium to nitrate. This natural process supplies energy to
327 the nitrifying bacteria. During the oxidation of ammonium to nitrite, N₂O is produced as a
328 by-product. Denitrification means the reduction of nitrate to di-nitrogen gas (N₂). During this
329 process N₂O is emitted to the atmosphere. The quantity of N₂O released from denitrification
330 depends on the environmental conditions - more or less N₂O is produced instead of N₂. The more
331 favourable the conditions for denitrification (e.g. completely water-saturated soil), the more N₂ is
332 proportionally produced. Changing the conditions (e.g. from wet to dry soils) favour N₂O release
333 [37]. Therefore, when soils start to dry out, more N₂O is emitted.

334 Therefore, it is obvious that nitrogen fertiliser industrial production and field application
335 contribute significantly to the total GHG emissions of agricultural production. An example of the
336 effect of nitrogen fertilisation is the allocation of the total GHG production from wheat when
337 cultivated in the economic optimum N rate shows that almost 90% of the total GHGs are associated
338 with N fertilisers (CO₂ and N₂O from production and N₂O from field nitrification and
339 denitrification).

340 A number of studies have concluded that many farmers apply nitrogen in excess of crop
341 nutrient needs [38,39,40]. According to Eurostat (2016) [41] in the period of 2005-2008 the average
342 nitrogen surplus coming from inorganic and organic fertilizers, manure and other nitrogen inputs,
343 like seeds and planting material, biological fixation by leguminous crops and free living organisms,
344 atmospheric deposition of the EU-28 member states was 51 kg N/ha that is an indication of the
345 amount of nitrogen fertilisation that could be diminished in EU agricultural production. It can be
346 that there is a trend of nitrogen surplus reduction as in the period 2009-2012 the EU-28 surplus was
347 reduced to 48 kg N/ha.

348 Therefore, if VR fertiliser application (including manure spreading) is used to provide nitrogen
349 to the crop according to the needs, then the final fertiliser (or manure) quantity will be reduced with
350 significant mitigation of both CO₂ (from fuel reduction timely fertilization and reduced weight of the
351 hopper) and N₂O from N fertiliser production and use (in the case of manure also CH₄ is produced).
352 Especially if the application is selected to be executed in the optimised conditions, then the reduction
353 of GHG emissions will be higher.

354 All VRNA technologies are interconnected to other PA technologies (GNSS, soil mapping,
355 canopy sensors, on-the-go sensors, machine guidance) and it should be mentioned that when these
356 technologies are combined in the proper way, the fertiliser quantity applied in the field is the
357 optimum, thus the emitted GHG are reduced. It should be noted that if N fertilisation is combined
358 with weather prediction regarding precipitation or appropriate irrigation scheduling (where
359 applicable), the result can be improved further.

360 Limited data exist on the GHG mitigation potential of VRNA. However, there is significant
361 work on the impact of lower nitrogen field input to N₂O emissions. Bates et al. (2009) [42] identified
362 an abatement potential of 5% reduction in the baseline GHG emission rate that is assigned to mineral
363 fertiliser application. They also pointed out that there is abatement by making effective allowance
364 for manure and residual N with VRA technology and can reach also a 5% GHG emission reduction
365 to the baseline emission rate for mineral fertiliser application. Millar et al. (2010) [39] have found that

366 nitrogen fertilizer application rates correlate well with N₂O emissions. However, the relationship
367 between nitrogen application and N₂O emissions is not necessarily linear [43,44] and the relationship
368 of N₂O emissions to nitrogen application rate increases proportionally with the application rate [21].
369 Another study estimated that an average of 1.19% of nitrogen added to soils is released as N₂O [45].
370 Paustian et al. (2004) [46] pointed out that as cropped soils emit N₂O at a rate of 0.2–3% of their
371 nitrogen inputs, when nitrogen inputs are decreased N₂O emissions could be reduced directly by
372 approximately 1.25% of nitrogen inputs saved. . Sehy et al. (2003) [47] examined the use of VRNA
373 and GPS in field nitrogen application and found out that N₂O emissions decreased by up to 34% in
374 low-yielding areas.

375 5.1.3. Impacts of the use of VRNA on productivity and farm economics

376 Farm productivity is influenced by nitrogen fertilization rates, as it is one of the most significant
377 parameters for increasing yield, while nitrogen constitutes an essential factor of farm economics.
378 Sogaard and Kierkegaard (1994) [48] described the relation between nitrogen supply and plant yield
379 with a quadratic equation. The parabolic shape reflects that each further added unit of nitrogen
380 causes smaller yield increase of the crop. At a certain point, the benefits of an added unit of nitrogen
381 (i.e. extra crop yield) barely outweigh the costs of this unit, and an economic optimum is reached.
382 This economic optimum is found at lower application rates than the yield optimum. By fertilising
383 each management zone near the economic optimum, higher returns can be achieved. Thus, the
384 highest returns for VRT application are expected on fields with high and spatially variable nutrient
385 requirements [49].

386 Excessive application of nitrogen fertilisation decreases financial returns and increases the
387 potential for nitrogen leaching into the environment. Insufficient application can reduce yields and
388 net farm income [40]. A landowner who benefits from fertiliser savings and yield gains would not
389 require additional incentives, although yield losses would require additional incentives. Additional
390 revenue gains could be realized with decreased need for fuel, labour, or other chemicals [50].

391 Several authors have analysed the impact of VRNA on farm productivity and economics. Tekin
392 (2010) [51] estimated that VRNA can increase Turkish wheat production between 1-10% offering
393 savings in nitrogen fertilisation between 4% and 37%. He also made an economic analysis using the
394 prices of the VR equipment, the fertilisers and the price of the wheat seed and found out that the
395 investment cost over a 5-year depreciation period would vary between €11.45 and €115.39 for a 500
396 ha and 50 ha farm size. Koch et al. (2004) [52] found also similar results (6-46%) in nitrogen savings
397 in corn fields in northeastern Colorado, USA. According to ICF International (2013) [50], VRT in
398 fertilisation was found to produce economic benefits through increased yields, improved crop
399 quality, and decreased fertiliser applications. This report states that 8% increase in wheat yields (for
400 10% less nitrogen) and 5% increase in corn yield (for 21% less nitrogen) was shown when
401 GreenSeeker technology was used in Maryland. In Virginia, using again GreenSeeker technology in
402 corn fields resulted in nearly 27 kg/ha less nitrogen application than the conventional method with a
403 nearly equivalent yield. GreenSeeker technology costs €17,616-€19,378, depending on whether
404 farmers already have electronic flow control technology on their fertiliser application equipment.
405 Based on the GreenSeeker price, current fertilisers prices and the reduction mentioned above from
406 the results from Maryland, the capital cost per acre for small farms was €77.5, for medium farms
407 €35.23 and for large farms €19.37.

408 HydroSense project (2013) [53] identified that the simpler form of precision farming in cotton
409 was by using N sensors to estimate uniform application of fertiliser through pre-existing drip
410 irrigation systems resulted in a net benefit of 113 €/ha/year. A variable-rate irrigation system applied
411 in the drip irrigation circuit resulted in a net benefit of 310 €/ha/year, while the net benefit climbs to
412 480 €/ha/year when deploying the emerging real-time and variable-rate technology for N inputs
413 even though the farmer needs to make significant investment on new equipment. It should be noted
414 that the VR fertigation technique (fertilization + irrigation) can only be applied in crops that are
415 irrigated using drip irrigation systems.

416 Compared to uniform application, in-season VR application of granular fertiliser at 1 m² spatial
417 resolution (based on optical sensing) increased their simple estimate of revenue (grain revenue
418 minus fertiliser cost) by 9.69€/ha when fertiliser was also applied before planting (fixed rate) and
419 more than 24.66€/ha when fertiliser was only applied in-season [49,54]. Mamo et al (2003) [55] found
420 a profit increase of 7 to 20.25 €/ha for corn when using VR fertilizer application compared to uniform
421 application due to reduction in the use of fertiliser. Koch et al. (2004) [52] found an increase of 25.6 to
422 38.6 €/ha in net returns for VRNA on Colorado corn based on site-specific management zones
423 compared to uniform application rates, both in a farmer and custom applied scenario.

424 Next to fertiliser costs also other costs can be attributed to VR fertiliser application, such as soil
425 sampling or online sensing, delineation of management zones, fixed or variable costs associated with
426 VR equipment (GPS receiver, on-board computer, software, VR system). However, the cost of these
427 equipment or services is not only associated with VR fertiliser application and is interconnected to
428 other PA applications. Larger farm sizes (economics of scale) allow fixed costs associated with VR
429 equipment to be spread over a larger area, and therefore decrease the expense of VR equipment per
430 hectare. VR application based on grid soil sampling has as a result the lowest net return, primarily
431 due to increased fertiliser uses and soil sampling costs [52].

432 Managing manure as fertiliser resource for crop production can increase the return for the
433 producer and the overall production efficiency of an animal-crop farming system in much the same
434 way as granular fertiliser management [56]. Precision management of manure has the potential to
435 further improve farming system production efficiency by applying the exact required manure
436 instead of inorganic fertilizers and increase the return to the farmer and minimizing the pollution
437 potential of animal waste that can be translated in profit as waste management becomes cheaper
438 [57]. As with VR granular fertiliser application, the key to VR manure application in general is the
439 existence of an application map, which is laborious and time consuming to generate when acquired
440 without sensor technology [58]. Although no literature is available considering the economic return
441 of VR manure application, many similarities with VR granular (inorganic) fertiliser applications can
442 be seen. The main difference is the fact that here the applied product is much bulkier, heterogeneous
443 and lower in nutrient content and financial value [57]. It should be noted that some VR manure
444 systems can be retrofitted to the tankers that farmers already have [36], which removes the need for
445 large investments to start with VR manure application.

446 Variable rate (VR) lime (which is primarily CaCO₃) application can increase crop yields and the
447 economic return of the farm [59]. Lime application increases the soil pH to a desired level and an
448 optimal pH level in the soil is important to achieve optimum yields and consistent quality [60]. Also,
449 lime improves the uptake and availability of plant nutrients and can also improve water penetration.

450 VR lime application can lead to improved adjustment of soil acidity at a lower cost and with a
451 (slightly) better yield response than uniform lime application [60]. Under-application of lime can
452 cause large yield losses. Over-application of lime can be as detrimental as under-liming [59], as it is
453 costly and can create problems with availability of some nutrients (for example inhibiting P and Zn,
454 or leading to toxic levels of Mn), disease pressure, reduced herbicide performance and herbicide
455 degradation [59,60]. Over- and under-liming cannot be avoided if lime is applied uniformly
456 throughout the field. It should be noted that VR liming appears to be only profitable for high value
457 crops [61], because even small effects of liming on yield produce favourable economic results in
458 these crops.

459 The main cost in a VR lime application is the cost of grid sampling. The actual amount of lime
460 used depends on the soil variability, field acidity, environmental factors, the sampling method and
461 the sampling resolution [59]. Weisz et al. (2003) [59] concluded that when performing grid sampling
462 and VR lime for 3 consecutive years in Piedmont no-till soybean fields, the net loss is €11.44/ha
463 compared to uniform lime application. However, when they performed grid sampling only in year 1
464 and 3, and performed the VR lime in each year (with year 2 based on the PH map of year 1) this turns
465 into a net gain of €4.28/ha over 3 years. Similarly, using the pH map from year 1 to apply lime for 3
466 years only in the areas where lime was initially required leads to a net gain of €6.44/ha estimated.

467 Field studies have shown that variable rate application of lime, as opposed to uniform
468 application, increases soil pH, reduces in-field variability and increases soybean yield but not corn
469 yield [62]. In 75% of the studies (4 in total) reviewed by Lambert and Lowenberg-DeBoer (2000) [63]
470 investigating VR lime, a positive economic effect was found, while in 25%, the articles indicated
471 mixed results. The lime application can be more effective in legumes than in corn and wheat, as the
472 response of the latter is limited to pH 5-5.5, where in legumes this can go up to pH 6 [59]. Kuang et
473 al. (2014) [60] found an increase in lime consumption but also an increase in yield and net profit
474 (€3.61/ha) for the VRT approach compared to the traditional approach for Danish spring barley.
475 BonGiovanni and Lowenberg-Deboer (2000) [64] found an increase of €6.51/ha for Indiana corn and
476 soybean production systems.

477 5.2. Variable rate irrigation (VRI)

478 5.2.1. Description of VRI technologies

479 Variable rate irrigation (VRI) can either be executed using a retrofitted self-propelled irrigation
480 systems or more recently micro-irrigation. The main types of self-propelled irrigation systems are
481 centre pivot and linear move sprinkler systems that apply water above the canopy of the irrigated
482 crop [65]. The most used self-propelled irrigation systems are the Mid Elevation Spray Application
483 (MESA) with irrigation efficiency of 85%. New developments are the Low Energy (elevation)
484 Precision Application (LEPA) and Low Energy (elevation) Spray Application (LESA) with irrigation
485 efficiency around 97% [66].

486 VRI systems are commercially available and can easily be retrofitted onto moving sprinkler
487 systems. There are different methodologies available to deliver varying irrigation amounts along a
488 lateral. One approach is to use parallel sprinkler control [67,68] or multiple manifolds; each valved
489 separately [69,70]. Another is to regulate the flow of water through each sprinkler drop hose by
490 controlling the “on/off” cycle of a hydraulic valve positioned above the drop hose [71,72,73]. A third
491 design changes the cross-sectional area of a sprinkler nozzle by cycling a retractable pin in and out of
492 the nozzle in a controlled manner [74].

493 The most common site-specific sprinkler irrigation systems in use today are speed control
494 systems [75]. However, zone (=boom section) control systems can achieve the same effects provided
495 by speed control, but with greater flexibility, and provide more management options. In Europe,
496 both centre pivot and linear move sprinkler systems are applied with a preference in the latter, in
497 contrast to USA where centre pivot is the most common.

498 Micro-irrigation, a high-tech type of VRI system, (drip or trickle emitters, micro-sprinkling &
499 microspray, subsurface irrigation) is used in areas with very scarce water supply where high value
500 crops are installed (orchards, vineyards), as they increase crop yield, use more efficiently water,
501 maintain warmer soil temperature and might result in less pesticide use [76]. This type of VRI is
502 ideal for Mediterranean EU countries, where drip irrigation is already in extensive use due to water
503 scarcity and such systems reduce further irrigation water use.

504 5.2.2. GHG emission reduction potential through VRI

505 The contribution of VRI in GHG emissions is very important because the reduction in water use
506 combines lower pumping energy needs and proper irrigation scheduling does not allow extreme soil
507 water availability that promote N₂O emissions.

508 Computer simulation studies comparing conventional and “optimized” advanced site-specific
509 zone control by centre pivot irrigation have reported water savings of 0–26% [75] that affect also
510 GHG emissions as stated above. However, water savings depend very much on the soil (sandy soil
511 will generate substantial water savings but heavy soils not (compared to surface irrigation systems).
512 Even though, lower quantities of water irrigation is translated to lower pumping needs which is
513 powered by either fossil fuel motors or electricity (indirectly producing GHG emissions if it is
514 provided by fossil energy).

515 A review by Trost et al. (2013) [77] compared N₂O emissions from irrigated and non-irrigated
516 fields and showed that availability of reactive nitrogen compounds controls increased N₂O
517 emissions under irrigation, in most cases. Increases of about 50% to 140% in N₂O emissions were
518 reported. This shows that VRA irrigation may significantly influence N₂O emission from irrigated
519 soils.

520 VR irrigation systems are based on reading coming from soil moisture sensing georeferenced
521 using GNSS receivers in order to cover the water needs of the plants (keeping soil moisture between
522 permanent wilting point and field capacity). Meteorological prediction of precipitation does not
523 allow irrigation preceding a rainfall. Therefore, irrigation scheduling can also provide the time
524 window for fertilisation to be executed in order to avoid provoking more GHG emission production
525 through N₂O.

526 5.2.3. Impacts of VRI use on productivity and farm economics

527 VRI systems have been tested to identify their direct impact on water use reduction and indirect
528 impact on farm productivity and economics. VRI systems can provide 8-20% reduction in irrigation
529 water use [78]. LaRue and Evans (2012) [79] using centre pivot speed control determined that
530 irrigation efficiency (the ratio between irrigation water actually utilized by growing crops and
531 water diverted from a source) can be increased by more than 5% while if speed control is also
532 combined with zone control then the irrigation efficiency can be further improved by 14%.
533 HydroSense project [53] applied VRI in three experimental fields with cotton in Greece and showed
534 that variable irrigation in cotton cultivation achieved 5 to 34% savings in water consumption with
535 yield impact that was rated between -18% to +31%. As a result, water use efficiency showed variation
536 between -12% to +54%. It should be noted that negative results were only shown in one field that did
537 not affect the total positive impact of VRI. They also calculated that VRI adoption in drip irrigation
538 may cost up to 40€ per ha.

539 Few hard figures are available about the economics of variable rate irrigation. LaRue and Evans
540 (2012) [79] reported that speed control in pivot systems is simply activated by changing the control
541 unit of the system with a cost of €1,321-2,202. As for zone control is a more complex system that can
542 reach an investment of €10,570 up to €24,663. Tomaszewicz et al. (2013) [80] indicated that VRI
543 modification of centre pivot with control system may cost between €13,212 and €35,233. They also
544 mentioned that in 2013, 200 centre pivot systems (around 0.1% of all installed US pivots) were VRI
545 enabled. However, it may be expected that adoption will be crop-value related: adoption will go
546 faster in high-value crops. Threshold prices can be calculated for specific crops. E.g. for precision
547 irrigation in the Texas High Plains, it was calculated the threshold of cotton price to be set above
548 €1.40/kg to make the use of precision irrigation profitable [81].

549 Lambert and Lowenberg-DeBoer (2000) [63] reported economic benefits of the use of VRI, more
550 specifically on corn yield and on water use efficiency. However, these benefits were not described in
551 numbers. As mentioned above, VRI systems can add significant cost to a farm, but additional
552 benefits have been identified by the installation of such systems, such as possible yield increase,
553 work load reduction, water use reduction and even pesticide use reduction, especially in climatic
554 unfavourable years like in big draughts [78,82,83]. For water use reduction, Hedley and Yule (2009)
555 [84] tested different scenarios for New Zealand and showed significant potential water savings of
556 21.8–26.3% for VRI, while these potential water savings suggest that VRI will become more
557 affordable as irrigation costs increase. Daccache et al. (2015) [85] estimated the benefit to the grower
558 in the reduced cost of water and energy to be typically around 30 €/ha to areas that are over-irrigated
559 in humid climates. These authors also claim that the development and uptake of PI would need to be
560 justified more in terms of the wider benefits to crop quality and reduced environmental impacts.

561 Currently, no economic data about VR micro-irrigation is available because VRI combined with
562 micro-irrigation is still in its infancy.

563
564

565 5.3. Machine guidance (MG)

566 5.3.1. Description of MG technologies

567 Machine guidance refers to the applications of GNSS for steering and guidance through two
568 main systems: driver assistance and machine auto-guidance. Driver assistance helps the driver keep
569 his line in the field through add-ons that are not integrated in the tractor's systems and can be
570 simply installed. The most common driver assistance system is the lightbar guidance system that
571 consists of a horizontal series of Light Emitting Diodes (LEDs) in a plastic case in front of the
572 operator, so he or she can see the accuracy indicator display without taking their eyes off the field. If
573 the light is on the centreline of the lightbar, the machine is on target, while if a bar of light extends to
574 one side, the machine is off the path and needs to be corrected. Auto-guidance is a more advanced
575 navigation systems that have the additional benefit of automatic steer of the tractor, also called
576 auto-steering. Machine auto-guidance systems are integrated in the tractor's hydraulics and can
577 directly take over steering operations. These more advanced systems are coupled to on-board
578 computers that allow for headland steering, section control and that accept drive-maps (routing) and
579 task maps to operate implements. Auto-guidance helps farmers in avoiding gaps and overlaps in
580 multiple passes with the tractor, which is mainly caused by operator error or fatigue. It is the most
581 adopted PAT because the impact on the farm is measurable and accurate. However, farm size
582 matters for the technology to provide tangible results, especially in terms of environment.

583 5.3.2. GHG emissions reduction potential through MG

584 Guidance technologies improve pass-to-pass efficiency, reduce overlapping and application
585 gaps. Guidance can be used for many field operations such as seeding, tillage, planting, weeding,
586 and harvesting [86] and for enabling autonomous vehicles. Therefore, it is expected that all main
587 agricultural inputs (seeds, fertiliser and pesticides) will be reduced.

588 Guidance technology saves as standalone fuel of the self-propelled machine and inputs
589 (fertilisers, pesticides) even if implements used are conventional type. In case it is combined with
590 VRA of agricultural inputs, they are also reduced further. An example is the work of Shockley et al.
591 (2011) [87] where machine guidance during planting and fertiliser application led to cost savings of
592 approximately 2.4, 2.2 and 10.4% for seed, fertiliser and tractor fuel, respectively. This savings are
593 also translated to GHG emission mitigation. Guidance systems like lightbar and auto-steering can
594 reduce fuel consumption by 6.32% [88].

595 Machine guidance is based on high accuracy GNSS receivers and can be used with all kind of
596 VRT machinery. As GNSS increases the accuracy of field applications, it will increase the reduction
597 efficiency of the technology itself. As machine guidance is indirectly interconnected with the
598 recording technologies, this combination is expected to reduce GHGs.

599 5.3.3. Impacts of MG use on productivity and farm economics

600 Guidance systems like lightbar and auto-steering can benefit crop growers by reducing
601 working hours as operators in the field) of 6.04% and reducing fuel consumption of 6.32%,
602 respectively [88].

603 In peanut digging operations a study revealed average net returns between 83 and 612 €/ha for
604 the use of auto-steering [89]. More particularly, they identified that increasing the peanut digger
605 efficiency by accurate placement over the target rows could minimize damaged pods and yield
606 losses. Therefore, they studied row deviation between manual driving (90-180 mm) and RTK
607 auto-steering system (0 mm). Data showed that for every 20 mm row deviation, expected yield loss
608 was 186 kg/ha. When RTK auto-steering system was used the expected additional net returns from
609 row deviation of 90 mm was 83 to 356 €/ha and from row deviations of 180 mm was 285 to 612 €/ha.

610 An economic analysis of farms adopting auto-guidance systems showed that systems with
611 inaccuracies below 2.5 cm are most profitable for larger farms, while systems with less than 10 cm
612 inaccuracy are a better economic alternative for smaller farms [90]. The accuracy level of these

613 systems is based on the quality of differential correction and internal data processing (as the
614 accuracy improves, the corresponding cost increases).

615 Farmers identify as the most frequently mentioned disadvantage of machine guidance the
616 up-front cost [91]. Machine guidance has scalable cost according to the accuracy obtained from each
617 system. When a GNSS device is already held by the farmer the cost starts from €1,320. Commercial
618 applicators that require a system that combine recording of all operations (to different customers)
619 together with full navigation can reach more than €12,770. A fully automatic navigation system with
620 operator engagement only at field ends could range from €5,284 to €44,040. It is important to select
621 between simple swathing aids like foam-marker systems that cost between €440 and €2,642 and
622 machine guidance systems. As a rule-of-thumb, a navigation system could cost six times more than a
623 foam-marker system, which means that justification for GPS navigation over foam markers must be
624 computed from the benefit side.

625 Machine guidance can have a variety of indirect economic impacts that are due to the accurate
626 application of different agricultural practices. For example, it is complicated to estimate the
627 economic impact of sprayer skips as influence of weed control on crop yield varies by crop and weed
628 population and long-term weed seed-bank effects have to be evaluated and assessed. When a field is
629 relatively weed-free, the skip impact to yield-loss might be minimal, but in a heavily infested field
630 the yield may drop to almost zero in the skipped area. The most important about pesticide
631 application gaps in economic terms is the creation of a weed seed bank all through the field that will
632 lead to management problems and greatly increased weed control costs in future years. Another
633 case is the impact of application gaps in fertilizer application, because skipping a part of the field is
634 more costly in a high-value crop (fruits and vegetables) than in a bulk commodity such as corn,
635 soybeans, or wheat. Similarly, lime application gap impact in yield in a field at pH 5.8 will probably
636 be low during the first year, but will increase in later years [91].

637 5.4. Controlled Traffic Farming (CTF)

638 5.4.1. Description of CTF technology

639 Controlled Traffic Farming is a system which confines all machinery loads to the least possible
640 area of permanent traffic lanes. It is based on machine guidance, but it keeps record of each field and
641 application in order to follow the same route every year. CTF allows optimised driving patterns,
642 more efficient operations (i.e. reduced overlaps) and targeted input applications. It increases
643 sustainability by reducing soil compaction and allows farming intensification as it prevents yield
644 loss, nutrient and water efficiency reduction, soil degradation and alleviation costs.

645 5.4.2. GHG emission reduction potential through CTF

646 CTF can reduce GHGs emissions as it affects the quantity of agricultural inputs used in field
647 operations (fuel, fertilisers, and pesticides). A study on the potential impact of site-specific
648 application and controlled traffic systems implemented on larger farms in Denmark (300 ha and
649 above) has stressed how a reduction of fuel costs by 25-27% in cereals can be traced back to a lesser
650 overlap, but also how 3-5% savings in fertiliser and pesticide in cereals can be obtained (when
651 fertilizers and pesticides are applied in a conventional manner) [92]. In the same work, fuel
652 reduction is mainly due to ease of cultivation (loose soil due to minimum compaction) and of course
653 due to minimum overpassing. Better soil structure means that conditions will be more favourable for
654 gases that are absorbed into the soil (e.g. CH₄) and to prevent harmful gases being produced through
655 anaerobic conditions, such as N₂O and CH₄, both of which are particularly damaging to the
656 environment. The greater number and larger size of pores in a non-trafficked soil means that more
657 water infiltrates and is captured within the profile. This means that not only is there less potential for
658 run-off and erosion but also that there will be more plant available water that will probably increase
659 yield. Higher yields can be translated into increased carbon stock in the crop itself, but also will
660 reduce GHG emission intensity as even if all agricultural inputs remain constant their ration with
661 yield will decrease.

662 Tullberg (2016) [93] has analysed the impact of CTF in GHG emissions directly and indirectly,
663 by reducing energy inputs, facilitating zero tillage and increasing fertiliser efficiency. Primarily, he
664 referred to fuel energy that in comparison to conventional, tillage, tractor fuel requirements of
665 uncontrolled traffic zero tillage and controlled traffic zero tillage farming are reduced by
666 approximately 40% and 70% respectively. The CTF effect is a result of improved tractive efficiency
667 and reduced draft at planting, reduced rolling resistance at harvest and spraying operations, and the
668 total elimination of tillage. Then, he went through herbicide energy, where he explained that there is
669 work in literature about how zero tillage affect herbicide energy requirements, but not about how
670 CTF reduce herbicide requirement. According to this author, the reduction is due to more timely
671 spraying from permanent lanes and the overall mean reduction can reach 25%. Fertilizers were also
672 referred, as in CTF they are not applied to permanent wheel tracks, which is translated to fertilizer
673 cost reduction of 10-15% for narrow-spaced crops, while yield increases by about the same amount.
674 CTF will also increase nitrogen efficiency (40-80%) due to reduced soil compaction and improved
675 soil biological activity when CTF is applied. In addition, as nitrogen fertilisers are applied at seeding
676 time in a moist compacted seed zone with limited drainage, it is expected that denitrification is
677 increased and as a consequence N₂O will also increase. However, CTF will minimise this problem
678 because it reduces seed zone compaction and waterlogging and allows the farmer to split fertilizer
679 applications with denitrification reduction as a side effect. Finally, it was explained that CTF
680 increase soil carbon stock as it reduces soil disturbance and improves the potential for cropping to
681 mimic natural vegetation in maximising dry matter production (and water use) by
682 double cropping or cover cropping.

683 5.4.2. Impacts of the use of CTF on productivity and farm economics

684 Heavy machinery passing on soil causes damage mainly due to compaction especially in wet
685 conditions. If traffic is reduced or stopped, soil becomes more friable, it requires little or no tillage
686 and its structure gets better year after year. CTF reduces compaction by confining wheels or tracks to
687 the least possible area of permanent traffic lanes. CTF is used to create and maintain healthy soils
688 and crops in combination with sustainable farm profit. CTF typically releases 57-115 €/ha extra profit
689 including the required investment, cost savings and increased yields [94]. Investment has to do with
690 the machine guidance installed in the agricultural machinery in use (tractors, self-propelled
691 sprayers, harvesters) and it was analysed in machine guidance section. Cost savings include
692 improved field efficiency, less tillage and significant capital savings on machinery due to lower
693 powered tractors needed.

694 Field efficiency is increased by reducing agricultural inputs and simultaneously increase yield.
695 Using CTF can decrease fertiliser use by 10-15% for narrow-spaced crops and pesticide reduction
696 can reach 25% [93]. Horsch (2016) [95] pointed out that fuel use for crop establishment with CTF is
697 reduced by at least 35%, while Jensen et al. (2012) [92] estimated that it may be possible to reduce
698 costs of fuel by 25-27% in cereals due to less overlap. Horsch (2016) [95] also mentioned that time
699 and energy for crop establishment can even be reduced by 70%, while he mentioned that CTF
700 increase yield about 15% more (averaged across 15 crops) than randomly trafficked soils as a result
701 of improved root growth that uses water and fertiliser more efficiently. CTF is focused on the
702 compaction where the system in Australia already is showing yield gains of 15% in sandy soils and
703 5% in heavier soils. A 1400 ha wheat/oilseed rape rotation farm converted from minimum tillage
704 farming to CTF no tillage was studied and it was found out that yield was increased by 4% in wheat
705 and 7.5% in oilseed rape [96].

706 In addition, machinery costs are reduced as lighter machines with less power are needed. Some
707 farmers in Australia have cut their machinery costs by as much as 75% while their crop yields have
708 risen [96]. Horsch (2016) [95] explains that CTF planning can lower the costs, because on the one
709 hand existing equipment may be enough for the new farming system and on the other farmers
710 converting to CTF can sell a lot of their equipment and invest in lower powered tractors (15% more
711 profit and 20% reduction in machinery costs have been recorded).

712 Blackwell et al. (2013) [97] reported that the total cost for adopting CTF varies significantly from
713 farm to farm due to farm's equipment level. It ranges between €21,140 and €52,850, while 21% of the
714 Australian farmers used CTF in 2011. A 1400 ha wheat/oilseed rape rotation farm converted from
715 minimum tillage farming to CTF no tillage was examined and it was found out that farm profit was
716 increased by 8% and the return on capital investment was 14% [96]. It was also shown that €290,000
717 savings on machinery investment was achieved. The cost of UK consultants for providing farm
718 survey to the farmer, including the present production constraints, the machinery and equipment
719 requirements to apply CTF was estimated to €927 plus expense and VAT. If the farmer requires a full
720 action plan to install CTF the service cost is increased to €1,390 plus expense and VAT [96].

721 5.5. Variable rate pesticide application (VRPA)

722 5.5.1. Description of VRPA technologies

723 Variable rate pesticide application (VRPA) technologies enable changes in the application rate
724 to match actual or potential pest stress in the field and avoid application to undesired areas of the
725 field or plant canopies [98]. In some cases, they can also be used to apply fertiliser at variable rates
726 [99].

727 There are two types of VR pesticide application technology. The map-based VR pesticide
728 application adjusts the application rate based on a prescription map, using a GPS receiver to identify
729 the field position and the input concentration is changed as the applicator moves through the field
730 [34]. The real-time sensor-based VR pesticide application changes the application rate using the
731 current situation of pest stress or canopy characteristics that is identified by the difference on colour,
732 shape, size, texture, reflectance, and temperatures of pests that is detected by different sensor types
733 (colour cameras, photodetectors, laser scanners, multispectral and hyperspectral cameras, thermal
734 cameras, and ultrasonic sensors). The sensor input can also be used to control the direction and rate
735 of chemical application [98]. VR pesticide application technologies use other PATs (GNSS, machine
736 guidance, crop sensing, and leaf wetness sensors) to apply the optimum pesticide quantity
737 site-specifically.

738 5.5.2. GHG emission reduction potential through VRPA

739 Pesticide application using variable rate technologies have the advantage of applying reduced
740 quantities of pesticides, not exceeding the application rate indicated for the diagnosed disease (e.g.
741 fungicides), or enemy (e.g. insecticides) or weed type (e.g. herbicide).

742 This means that the crop yield will not be affect negatively, as the enemy or rival will be treated
743 at lease as efficiently as before. At the same time, the reduction of chemical application will affect the
744 quality of the final product that could increase farm profitability due to increase product prices.

745 The environmental benefits from pesticide application reduction are numerous as ground and
746 water contamination is reduced and the influence on biodiversity becomes lower [100]. In addition,
747 limiting insecticide use and precision application of pesticides to only infested spots, provide floral
748 resources and shelter habitats that can increase the abundance, diversity and fitness of natural
749 enemies, decrease pest damage, increase crop yield and the farmer's profit [101]. There is significant
750 work on the saved pesticide quantity that ranges from 11 to 90% for herbicide use in different arable
751 crop types [100,102,103,104]. Other work recorded pesticide use reduction in perennial crops
752 between 28- 70% [105,106,107,108]. VR pesticide application can also cause reductions in insecticide
753 use by 13.4% in winter wheat [109]. They also reduce significantly spray overlap that can also reduce
754 the total pesticide use [110].

755 The impact of the high pesticide reduction shown from the literature is environmentally
756 significant, but in terms of GHG emission reduction the contribution of this technology to the total
757 agricultural effect is slight. The reason is that in this case GHG emissions are mitigated only during
758 the industrial production of the pesticide. Even if the index of GHG emission production for every
759 kg of pesticide is very high in comparison to other agricultural inputs (seed, fertilisers, fuel), the total
760 applied quantity is very low mirroring in a low total impact on GHGs [111].

761 5.5.3. Impacts of the use of variable rate pesticide technologies on productivity and farm economics

762 Benefits of variable rate pesticide spraying are mainly associated with savings on pesticide use.
763 Since most research has been done in the area of herbicide application (vide supra), the focus of this
764 section lies on the economic impact of VR herbicide application.

765 Oriade et al. (1996) [112] suggest that weed patchiness is the most important factor
766 economically justifying the use of site-specific weed control. Using simulation, they show that
767 economic and environmental benefits are almost zero at low weed pressures, particularly if weeds
768 are evenly spread. The benefits were larger as weed populations and level of patchiness increased.
769 At high weed patchiness, return values of 17 €/ha to 33 €/ha were found in corn and soybean. The
770 authors concluded that returns from site-specific management of less than 14 €/ha are not sufficient
771 to warrant the practice. The costs of information collection, time application effects, and human
772 capital were not considered in this model.

773 Besides pesticide saving, more savings are possible from shorter times per hectare for filling the
774 tank and carrying the spray mixture to the field by reducing the volume that is needed per hectare
775 [100].

776 Swinton (2003) [113] states that research results on the profitability of site-specific weed
777 management are very variable, because certain studies focus only on potential reduced cost from
778 less herbicide spraying while ignoring the increased capital cost of variable rate application
779 equipment and the increased variable cost of information processing. Other studies do take these
780 last two factors into account, which results in more realistic numbers on profitability. Timmermann
781 et al. (2003) [100] found that the monetary savings resulting from the reduction in herbicide use
782 varied between crops, depending on the amount of herbicides saved and the price of herbicide. In
783 maize, winter wheat, winter barley and sugar beet, savings of respectively 42 €/ha, 32 €/ha, 27 €/ha,
784 and 20 €/ha were realised. In this regard, savings also depend on the different economic thresholds
785 for pest control and the different competitive power of the crops. Batte and Ehsani (2006) [110]
786 estimated spray material savings of about 4 €/ha for a map-based spraying system compared to a
787 self-propelled sprayer without any form of GPS for guidance assistance or sprayer control. The
788 magnitude of input savings further increased as waterways were added to the field. Those authors
789 also calculated the costs of the map-based spraying system: 2911 €, 3004 € and 3096 € per year in
790 extra costs for sprayers with a boom width of 18.3, 27.4 and 36.6 meter, respectively. Most of the
791 costs are related to the fixed investment which diminishes per hectare as farm size increases. They
792 also conclude that the benefits increase proportionally to the cost of the pesticide being applied, the
793 number of annual applications, and to the driver error-rate of the non-precision spraying system.

794 Gerhards and Sökefeld (2003) [114] evaluated the economic benefits of a real-time, automatic,
795 site-specific weed control system compared to conventional field spraying. They found that
796 although the costs (fixed + variable) for the VRA technology were larger (9.56 €/ha vs. 5.20 €/ha), the
797 average costs for weed control were lower due to herbicide savings (32 €/ha vs. 68 €/ha in winter
798 wheat and winter barley, 69 €/ha vs. 148 €/ha in sugar beet, and 96 €/ha vs. 103 €/ha in maize). Based
799 on these economic calculations, Dammer and Wartenberg (2007) [104] comment that if sensors were
800 available on the market, it would be profitable for farmers to invest in variable rate technologies.

801 Costs of map-based VRPA are attributed to mapping, data processing, decision making and
802 site-specific application technology. Commercial mapping services typically charge 4.5 – 9.0 €/ha to
803 map field boundaries including waterways and other physical features [110]. Gerhards and Sökefeld
804 (2003) [114] estimated the costs of a direct injection system at 3.9 €/ha (in addition to the costs of the
805 sprayer) for weed control in sugar beet, maize, winter wheat and winter barley in a German study.
806 Batte and Ehsani (2006) [110] state that the extra cost of a precision sprayer equipped with
807 individually controlled nozzles based on GNSS information would be about €8,000. However,
808 Timmermann et al. (2003) [100] comment that several components of variable rate technology,
809 including GNSS, board computer and GIS, can also be used for other precision farming activities
810 such as planting, fertilisation and harvest, and can therefore not be considered as a cost that is solely
811 related to VRA pesticide application.

812 In contrast to map-based VRA, an additional step of generating an application map with the
813 help of GIS is not necessary. Therefore, there are no additional costs for computers, GIS software or
814 DGPS. However, the sensor technology can be very expensive, although cheap sensors are available
815 as well. Gerhards and Sökefeld (2003) [114] estimated the cost of a camera system for weed detection
816 at €40,000, whereas Dammer and Wartenberg (2007) [104] used an optoelectronic weed sensor of
817 about €2,000. The latter could however not distinguish between crops and weeds and was therefore
818 limited in its operations. In a study on maize-based cropping systems, experts within Europe
819 evaluated that precision spraying using GPS spray maps can result in a net profit within a time
820 frame of 3-4 years [115].

821 5.6. Variable rate planting/seeding (VRP/VRS)

822 5.6.1. Description

823 Variable rate planting/seeding (VRP/VRS) is the method of varying the rate of plants or seeds
824 according to local soil potential. Regular planters/seeder are based on the constant rate of plants or
825 seeds through a ground drive wheel, while VR systems is equipped with independent gear box or
826 hydraulic drive that is controlled according to the needs of the certain part of the field [34]. More
827 advanced systems have independent planting/seeding elements that can also differentiate the
828 application rate on-the-go per row [116]. A prescription map is required. VRP/VRS eliminate double
829 planting in headlands and point rows and in very heterogeneous fields redistribute within field
830 seeds in the optimum quantity. VRP/VRS can perform better in heterogeneous fields because seed
831 rate differentiation will affect the yield in low crop performance zones and the final output will be in
832 favour of the farmer.

833 5.6.2. GHG emission reduction potential through VRP/VRS

834 When applying VRP/VRS it is possible that the total plant/seed quantity used in the field will be
835 lower (less GHG emissions coming from the production of the plant or the seed) or the same as in
836 conventional seeding. Nevertheless, an effect of VRP/VRS on GHG emissions can be expected
837 through the increased yield [117]. Another means of GHG reduction is the decreased fuel required
838 for generating the same amount of harvest, since through VRP/VRS more harvest can be produced
839 on a given soil surface.

840 5.6.3. Impacts of the use of VRP/VRS on productivity and farm economics

841 The main benefit from VRP/VRS is an increase in yield (vide infra). The main factor driving the
842 economic performance of variable-rate seeding is soil variability. In very uniform fields, the return
843 on investment of VRP/VRS will be low, while in heterogeneous fields with differentiated
844 performance zones, the return on investment will be much higher. In the early years of VRP/VRS
845 development, its economic impact was unclear.

846 Variable seeding rate of winter wheat can offer increase in yield from 3% compared to uniform
847 seeding [118]. Another research showed that farmers using variable rate seeding have achieved an
848 average winter wheat yield benefit of 4.6% over and above farmers drilling at a flat rate. This makes
849 the average winter wheat yield benefit over the four years of study (2011-2014) to be 6.45% [119].
850 Corn yields can be increased by 6% using variable rate seeding [120]. Although VRS dates back at
851 the first years of precision agriculture movement it is now the time that its importance was
852 acknowledged by farmers. Specifically, 10-12% climb in acquisition of VRS drills and planters was
853 noticed in USA in 2007 [121].

854 Bullock et al. (1998) [122] observed differences in economically optimal plant densities for
855 different field qualities: they estimated that areas of the field with higher yield potential could
856 benefit from a higher plant density. At the time, they concluded that variable rate seeding would be
857 infeasible, because of the high cost associated with characterizing site variability. Another work
858 stated that the investments necessary for adopting variable rate corn seeding would only be
859 economically justifiable for farmers with some low yield potential land, where significant seeds

860 savings and yield gains can be made, but not for farmers with a mix of solely medium and high
861 potential land [123]. Taylor and Staggenborg (2000) [124] concluded that variable rate seeding was
862 only economically feasible on their fields of study if less expensive ways to generate the prescription
863 map were available or if corn showed a greater yield response to seeding rate. Shanahan et al. (2004)
864 [125] stated that “site-specific management of plant densities may be [ed: economically] feasible”,
865 most likely due to technological advances. Dillon et al. (2009) [126] performed sensitivity analysis
866 with respect to alternative soils, seed price, wheat price and cost of variable rate seeding technology
867 to determine the economic feasibility of variable rate seeding and concluded that the practice of VRS
868 of wheat in France is economically feasible. Hörbe et al. (2013) [117] performed two experiments that
869 tested the economic returns of VRS maize according to a prescription map with three management
870 zones, i.e. a low crop performance zone (LZ), receiving 31% less seeds/ha, a medium crop
871 performance zone (MZ), receiving the normal seeding rate, and a high crop performance zone (HZ)
872 receiving 13% more seeds/ha. This resulted in a yield increase of 1.20 and 1.90 tons/ha in the LZ of
873 the two experiments, and 0.89 and 0.94 tons/ha in the HZ. In the second experiment, carried out one
874 year after the first, in growing season 2010-2011, this resulted a partial net income (excluding extra
875 costs for the VR seeder) that was around 7% higher than in the same field seeded with a flat rate over
876 the entire field. 71.5% of this higher net income was gained in the LZ, although the LZ area was
877 smaller than the HZ area (22% vs 28% of the total field area, respectively).

878 A study of automatic section control systems in VR planters among 52 fields showed a
879 percentage of double-planted area to reach up to 15.5% and the savings from the use of VR planters
880 ranged from €3.5 to €22.9 per ha depending on the farming operation and the field type [127].

881 No independent scientific research on the economic impact of multi-hybrid planting/seeding is
882 currently available, because this technology has been developed very recently.

883 5.7. Precision physical weeding technology (PPW)

884 5.7.1. Description of PPW technology

885 Precision physical weeding (PPW) technology is the method of weed control through burning,
886 mechanical weed control with knives, discs, hoes or harrows with minimum crop damage and no
887 chemical herbicide use. The technology is still in its infancy, with some prototypes that use precise
888 guidance and detection systems being available.

889 The most promising approach for weed detection is a continuous ground-based image analysis
890 system that locate crop row in the field [128]. In this work is reported the design and
891 development of an automatic machine able to perform, at the same time, mechanical and
892 thermal weed control on maize. Other detection system would be ultrasonic sensors that detect plant
893 density that when it is increased the harrow treats this part more aggressively [129]. In this work, a
894 system for online weed control was developed. It automatically adjusts the tine angle of a harrow
895 and creates different levels of intensity (gentle to aggressive). A hybrid physical/chemical weeding
896 system is mentioned by Norremark (2010) [130]. A robotic physical weeding system is applied in
897 sugar beet that execute real-time weed infestation survey and apply 4 row intra-row precision weed
898 control implement combined with 4 row precision spraying (10% of normal herbicide dose rate). It
899 can also combine an inter-row weed control implement that increase its efficiency.

900 5.7.2. GHG emission reduction potential through PPW

901 Precision physical weeding technology might have an effect on reducing GHG emissions
902 through the production of the avoided pesticides. In the case of mechanical precision weeding, fuel
903 consumption will also be reduced (and the respective GHGs) because the tractor pulling the
904 weeding implement will confront lower draught forces coming from soil tilling when the angle of
905 the harrow tines will be less aggressive than with the conventional tillers [129]. In the case of
906 precision thermal weed control, the fuel for weed burning is expected to be lowered reflecting in
907 GHG emissions in comparison to conventional weed burning implements that have continuous
908 flame covering all field surface. However, if thermal weed control is applied in fields that the

909 conventional weeding is based in mechanical tillage then the GHGs from burning weeds will
910 contribute negatively in climate change. In addition, when conventional chemical weeding is
911 substituted from precision thermal weeding, the GHG emissions coming from pesticides reduction
912 will be partially compensated from the emissions emitted from weed burning. As in the case of VR
913 pesticide application, the impact on the avoided GHG emissions of the total agricultural system is
914 expected to be very low.

915 5.7.3. Impacts of PPW on productivity and farm economics

916 The hybrid mechanical/chemical system showed total estimated cost reduction for 10-year
917 depreciation and 5% interest rate was 12% (in particular 260 €/ha, while conventional weeding cost
918 297 €/ha) in a 80 ha field size working 667 hours per year. When the inter-row weed control
919 implement is added to the system, the cost reduction can reach 24%. This is due to the reduction in
920 total weed management costs compared to the conventional [130]. Peruzzi et al. (2008) [131] worked
921 on physical weed control in open field tomatoes by applying a rolling harrow and a flaming machine
922 in pre-transplanting together with precision hoeing in post-transplanting. It was noticed that yield
923 increased by 15-20% due to better weed management which resulted in 400-700 €/ha on top of the
924 normal harvest.

925 6. Conclusions

926 Climate change is a real fact and anthropogenic activities are one of the parameters accelerating
927 the phenomenon. Through the years, agriculture did not receive great attention in terms of GHG
928 emission production. In the recent past, detailed analysis of the impact of this sector has been
929 executed and several mitigation measures were proposed.

930 PA has several positive impacts on agricultural systems and recently there is significant interest
931 on the possible GHG emission mitigation through the use of PATs. However, literature is limited on
932 data regarding the effect of PA on climate change. All categories of PATs (guidance, recording,
933 reacting) contribute to the reduction of GHG emissions and in farm productivity and income due to
934 their interconnections and it is difficult to separate them according to importance. Recording and
935 GNSS technologies are supportive in the PA process, while reacting technologies and guidance
936 systems have a direct visible result on the agricultural system that are applied on. Hence, these PATs
937 were analysed according to their potential to reduce GHG emissions and improve farm productivity
938 and income.

939 Variable rate nutrient application (VRNA) technologies can reduce GHG emissions
940 significantly as the most influencing agricultural input are the fertilisers and especially nitrogen
941 fertilisers, which are the main source of N₂O that is the most influencing GHG derived from
942 agricultural activities. They can also affect positively farm productivity and income by applying the
943 right amount of nitrogen according to the plants' needs. Variable rate irrigation (VRI) systems
944 follows in GHG emission reduction potential as its impact is dual; primarily the decrease of irrigated
945 water reduces the energy for water pumping from the aquifer and secondly the optimum irrigation
946 scheduling affect significantly the GHG emissions derived from fertilisers through the soil (mainly
947 N₂O). In terms of productivity, the impact is also significant, particularly in dry areas, as irrigation
948 scheduling kai dosage can be optimized resulting in economic benefits (lower pumping costs
949 combined with higher yields). Controlled Traffic Farming (CTF) and machine guidance (MG) limit
950 the use of tractors to only the necessary passes through the fields avoiding overlapping with
951 respective decrease in agricultural inputs and fuel (translated into GHG emissions reduction and
952 lower cost of production). Variable rate pesticide application (VRPA) is also expected to have GHG
953 reduction potential due to lower pesticide application through lower GHGs coming from pesticide
954 industrial production. However, the actual environmental effect can be extremely significant, but
955 through lower chemical substances application that contaminates all natural resources (water, air,
956 soil). The effect on farm economics is also major, especially in crops that receive many chemical
957 applications, such as herbicides and fungicides. Variable rate planting/seeding (VRP/VRS) and
958 precision physical weeding (PPW) show lower, but not irrelevant GHG emission mitigation.

959 VRP/VRS is mainly important for optimising plant density in the field that can increase farm
 960 productivity, while the reduction in seed/plant population is associated with GHG emissions during
 961 their production. PPW reduces pesticide application and fuel used for flame burning of weeds.

962 There is a necessity that more research should be carried out on the impact of PATs on GHG
 963 emissions, as there is strong evidence that PA can significantly assist in reducing GHG emissions,
 964 which will also influence the further adoption of PATs by practitioners, however this impact should
 965 be numerically justified with field experiments.
 966

967 **Acknowledgments:** The research leading to these results has received funding from the European Commission
 968 - Joint Research Centre (JRC), Directorate D - Sustainable Resources - Economics of Agriculture the service
 969 contract 199163-2015 A08-NL. This work reflects only the author's view and that the Union is not liable for any
 970 use that may be made of the information contained therein. The cost of publication in open access was covered
 971 by the European Commission.

972 **Conflicts of Interest:** The authors declare no conflict of interest. The founding sponsors participated in the
 973 design of the study; in the writing of the manuscript, and in the decision to publish the results.

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